

Re-CoSKQ: Towards POIs Recommendation Using Collective Spatial Keyword Queries

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Introduction and goals

- Interest of recommender systems in mobile computing scenarios
- The location is a key spatial attribute:
 - Can techniques from the field of spatial databases help?
- Explore the potential use of Collective Spatial Keyword Querying (CoSKQ)

Proposal: Re-CoSKQ for the recommendation of POIs

- Semantic coverage of the query keywords (no exact match req.)
- Minimize the cost:
 - Distance to get to the POIs
 - Similarity between the query and the descriptions of items

$$\begin{aligned} U &= \{u_1, \dots, u_n\} \rightarrow \text{users} \\ O &= \{o_1, \dots, o_m\} \rightarrow \text{POIs} \\ o_i \cdot K &= \{k_1, \dots, k_j\} \rightarrow \text{keywords describing POI } o_i \in O \end{aligned}$$

Examples of distance functions

- Location distance:
 - Euclidean
 - L1-Norm / Manhattan
 - Geodesic distance (shortest path)
- Term distance:
 - Similarity based on concept closeness (relatedness)

$$sim(k_1, k_2) = 1 - \frac{sp(k_1, k_2)}{2D}$$

- Similarity based on closeness and concept depth

$$sim(k_1, k_2) = \begin{cases} e^{-\alpha l} \frac{e^{\beta h} - e^{-\beta h}}{e^{\beta h} + e^{-\beta h}} & \text{if } k_1 \neq k_2 \\ 1 & \text{otherwise} \end{cases}$$

• l: shortest path
 • d: depth of the least common subsumer
 • $\alpha, \beta > 0$: weights

Evaluation proposal

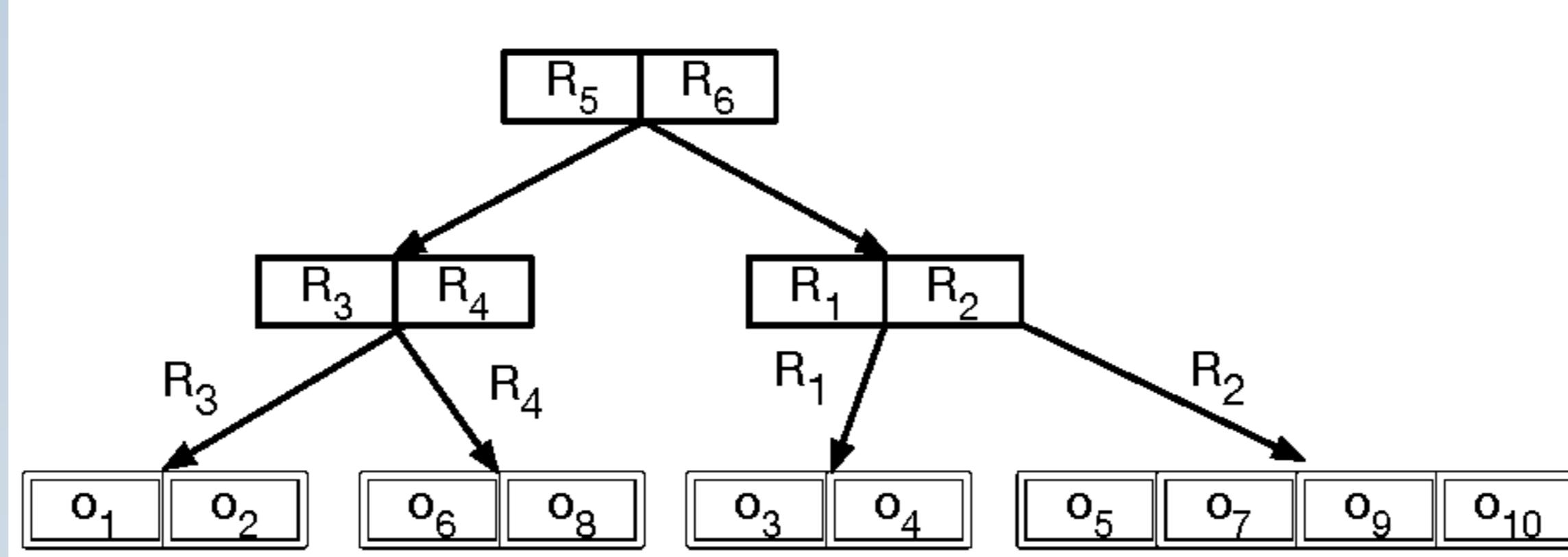
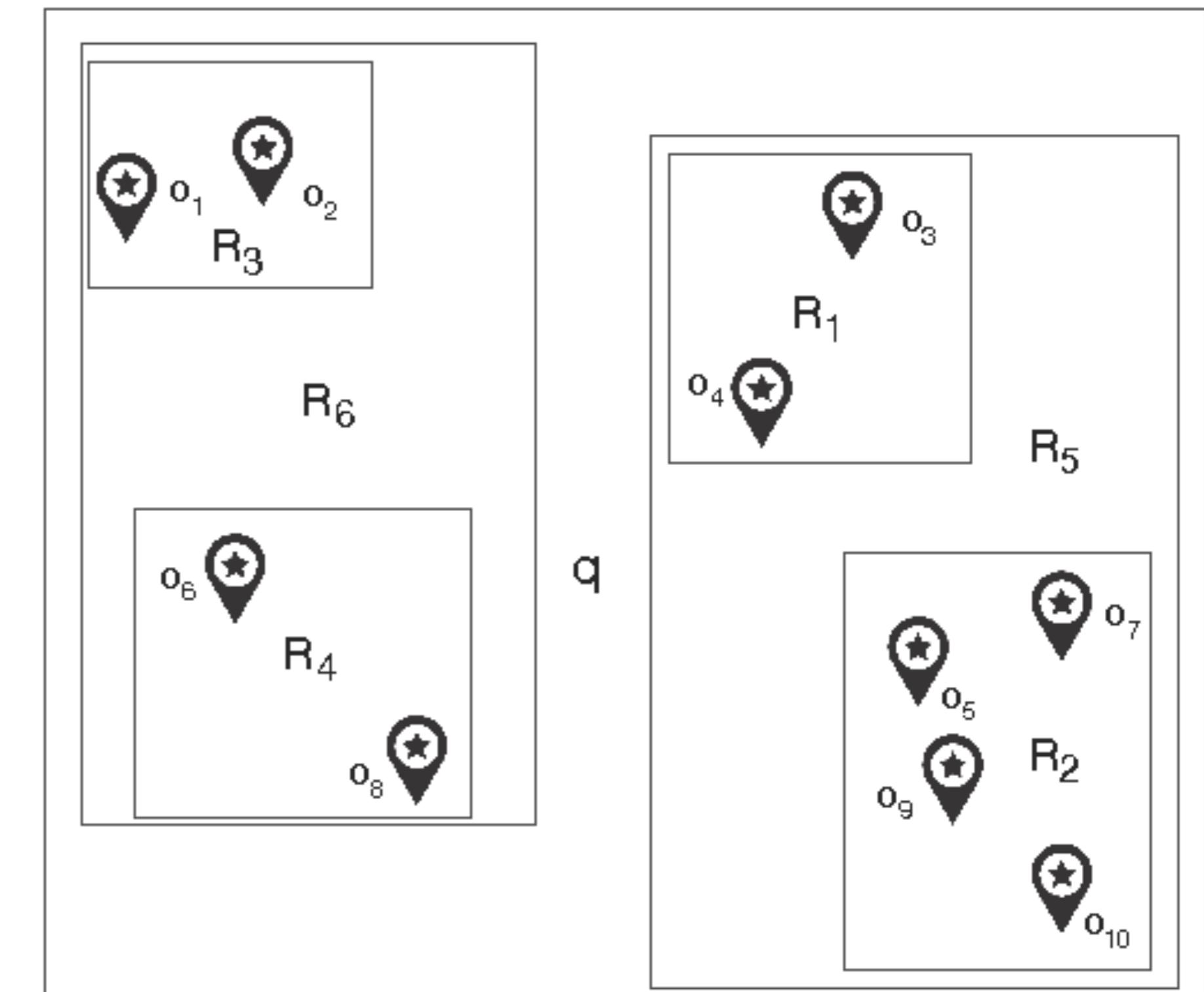
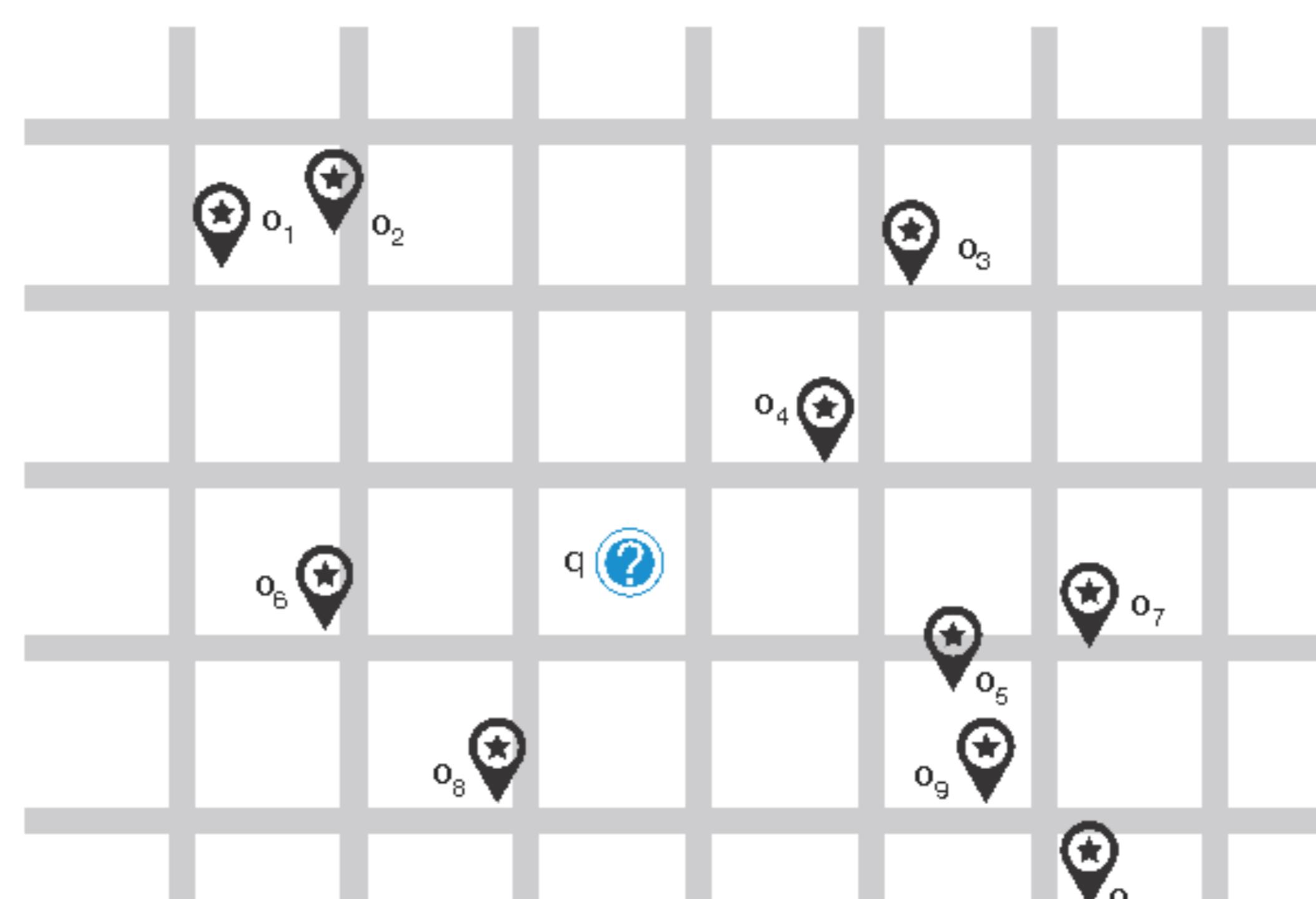
- Define a representative set of queries
- Annotate a dataset of POIs with predefined categories based on the keywords → ground truth → precision, recall, ... + performance and tuning
- Also interesting: user-centered evaluation, DataGenCARS

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Collective Spatial Keyword Querying (CoSKQ)

- Technique from the spatial databases field
- Goal: retrieve a group of spatial objects that collectively match the user preferences given:
 - Specific locations (of the user and also of the objects)
 - A set of keywords
- Use of IR-tree data structures (balanced trees that allow indexing objects and keywords)



Internal node:

- pointers to the child nodes
- a Minimum Bounding Rectangle (MBR) covering its subtree
- the set of all keywords in the subtree

Leaf node:

- items o (POI objects) in the node
- a bounding rectangle for each o
- a pointer to an inverted file with the keywords that describe each POI

Examples of cost functions

$$cost(q, \mathbb{O}') = \alpha \cdot \max_{o \in \mathbb{O}'} [dist(q.\lambda, o.\lambda)] + \beta \cdot \max_{o_1, o_2 \in \mathbb{O}'} [dist(o_1, o_2)] + \omega \cdot \max_{k_1 \in q.K, k_2 \in \cup_{o \in \mathbb{O}'} o.K} [dist(k_1, k_2)] \quad \leftarrow \text{TYPE 1 - COMB}$$

$$cost(q, \mathbb{O}') = \max \left\{ \alpha \cdot \max_{o \in \mathbb{O}'} [dist(q.\lambda, o.\lambda)], \beta \cdot \max_{o_1, o_2 \in \mathbb{O}'} [dist(o_1, o_2)], \omega \cdot \max_{k_1 \in q.K, k_2 \in \cup_{o \in \mathbb{O}'} o.K} [dist(k_1, k_2)] \right\} \quad \leftarrow \text{TYPE 2 - MAX}$$

$$cost(q, \mathbb{O}') = \alpha \cdot \min_{o \in \mathbb{O}'} [dist(q.\lambda, o.\lambda)] + \beta \cdot \max_{o_1, o_2 \in \mathbb{O}'} [dist(o_1, o_2)] + \omega \cdot \max_{k_1 \in q.K, k_2 \in \cup_{o \in \mathbb{O}'} o.K} [dist(k_1, k_2)] \quad \leftarrow \text{TYPE 3 - MIN-MAX}$$

$$cost(q, \mathbb{O}') = \left[\left(\alpha \cdot \left(\sum_{o \in \mathbb{O}'} (dist(q.\lambda, o.\lambda))^{\phi_1} \right)^{\frac{1}{\phi_1}} \right)^{\phi_2} + \left(\beta \cdot \max_{o_1, o_2 \in \mathbb{O}'} dist(o_1, o_2) \right)^{\phi_2} + \left(\omega \cdot \max_{k_1 \in q.K, k_2 \in \cup_{o \in \mathbb{O}'} o.K} dist(k_1, k_2) \right)^{\phi_2} \right]^{\frac{1}{\phi_2}} \quad \leftarrow \text{TYPE 4 - UNIFIED COST FUNCTION}$$

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